

Digital Controller

EBM-152070



- closed-loop and/or open-loop spreading
- · precisely metered deposition rate
- recording of spread data, including a protocol for use with GPS
- good adaptability for interfa. with hydraulic system
- good adaptability for interfa. with spreading system
- ergonomic user interface
- customised versions can be supplied

1 Description

1.1 Brief description

The EBM-152070 digital controller is available for general sale. It is designed for use with any make of single- or twinchamber salt spreader for winter road management.

The controller is intended for the following applications:

- Single-chamber unit with proportional liquid pump; a liquid proportion from 0% to 100% can be selected with a step switch
- Two-chamber unit with the facility for operating with blended materials
- Two-chamber unit with proportional liquid pump and additional on/off valve

All functions are controlled by a microcontroller. The system can be operated in "closed loop" or "open loop" modes, as well as in mixed mode. To fully exploit the advantages of the digital system (e.g. quantity measurements), the auger, belt and liquid pump should be run in closed-loop mode with this controller. If a function is controlled in open-loop mode, certain limitations in comparison to closed-loop mode must be accepted. Meter readings for both total and daily quantities of salt, liquid, sand and grit can be called up on a display. Further information on operating hours, spread distance, etc. can be provided. Interfaces for data transfer to a PC are also provided, as are the prerequisites for communication with GPS systems. Software for general-purpose salt/grit spreading is installed as standard. We can carry out application-specific modifications to suit customer preferences. The control panel can be laid out to suit the specific application and customer requirements.

2 Optional product functions

2.1 Spread-data recording

With the /01 option, the EBM-152070 digital controller maintains a record of entire spreading patrols. At what speed, and with what spread settings, was the vehicle driven? Was the flow of grit interrupted - and, if yes, by what? If suitable sensors are fitted, the EBM-152070 also accurately records the quantities deposited. Two protocols are available: the standard protocol and a GPS protocol. The standard protocol sends the recorded data via the serial interface to a printer or a PC data-capture program. This enables, for example, the invoicing justification for subcontractors to be gathered. (The design of the main protocol is explained in the Output Format section of the protocol specification.) Precise deposition means optimised use of the spread material and improved inventory management. Automatic fault detection ensures that vehicle defects can be rectified promptly. A GPS protocol is implemented; this can be used in vehicles that have a GPS reception system.

It not only captures and checks the spreading performance, but also provides planning and maintenance support to fleet managers, including visualisation of the routes patrolled. The data is recorded every 10 seconds. As well as determining positions, the distance driven and the exact geographical route patrolled can be established.

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2.2 Thermo-CTR (option /03 & /04)

The surface temperature of the road can also be used to regulate the amount of spread material being deposited. This function is known as Thermo-CTR (controlled). In conjunction with a temperature sensor in the form of an infrared

camera, the EBM-152070 with option /03 and /04 has 4 different automatic programs with which it can continuously meter the spread material. A minimum rate of deposition can be set. If the Thermo-CTR function is switched off, the normal spread function of the EBM 152070 is available.

3 Technical data

Characteristics		Description, value, unit		
Supply voltage U _B		12 V 30 V DC, smoothed. Ripple < 10%		
Inputs	2 analogue inputs	Actual value, spread-symmetry adjustment; R _i approx. 80 ks Actual value, Thermo-CTR (optional)		
	4 frequency inputs	Impulse inputs for feedback signals (NPN sensors) from spinner, auger/belt and liquid pump. max. input frequency $f_{max} = 1 \text{ kHz}$. input resistance R_i approx. 2 k Ω , aktiv low, $U_{High} > 10 \text{ V}$, $U_{Low} < 2 \text{ V}$		
	1 frequency input	For sensor for road-speed signal. can be set for NPN or PNP sensors or inductive AC sources. factory setting PNP, max. input frequency $f_{max} = 1$ kHz, input resistance R_i approx. 10 k Ω , standard signal form to DIN 9684. (option: adapter for road-speed signal $f_{max} > 1$ kHz)		
	4 on/off inputs (sensor inputs)	For spread-monitoring, brine empty and salt empty 1, salt empty 2 . NPN sensors: max. input frequency $f_{max} = 1$ Hz, input resistance R_i approx. 2 k Ω , active low, $U_{High} > 10$ V, $U_{Low} < 2$ V		
Outputs	4 proportional outputs	For demand-signal presets for spinner, Transport 1 and Transport 2. maximum output current 2.5 A		
	6 on/off outputs	For work headlights, warning beacons, wet salt, customer out- put (maximum current per output 5 A but max. combined total 10 A), and for spread symmetry left and spread symmetry right (additional output current max. 5 A)		
Display		Graphic display, LCD display, illuminated		
Outputs	Power supply + speed signal Actuators and sensors	42-pin plug HAN 42DD		
Special features		Reverse-polarity protected supply voltage input terminal		
Operating temperature		-40 °C +85 °C		
Reference voltage		Approx. 10 V max. 200 mA for power supply		
Control panel		back-lit		
Option: serial interface		SUB-D 9, 2400, 4800, 9600, 19200		
Protection class		IP30		



Characteristics	Description, value, unit
Certificate of electromagnetic compatibility	CISPR 25 Broadband disturbances (Annex 7) CISPR 25 Narrowband disturbances (Annex 8) ISO / TR 10605 Immunity to electrostatic discharge (ESD) ISO 7637-2 Immunity to copled impulses; (Annex 10) ISO 7637-2 Emission of interferences pulses (Annex 10)
Dimensions	B = 243 mm, T = 199 mm, H = 105 mm
Weight	approx. 3,5 kg

4 Ordering code

4.1 Digital controller

	Designation	Part number
Standard unit	EBM-152070-DS-WINT	100031512

We can carry out application-specific and client-specific modifications, particularly to the software.

The control panel can also be customised with a customer logo or different scaling, for example.

4.2 Accessories

42-pinplag/socket connection	Part No.	Standard	Alternative	Optional
Line housing, HAN-DD42, straight, PG16	100.607910	•		
Plug insert HAN-DD42	100.607761	•		
Contact pin for 0.14 - 0.37 mm ²	100.217466		•	
Contact pin 0.5 mm ²	100.217467		•	

5 Connection diagram





6 Description of function





Key / Display	Function / Meaning	
ERROR	Fault messages Audible and visible fault message for Container for Transport 1 empty FILL LEVEL 1 (when enabled) Container for Transport 2 empty FILL LEVEL 2 (when enabled) Liquid empty LIQUID EMPTY! Incorrect feedback from the spinner SPINNER ERROR! Incorrect feedback from Auger/Belt 1 BELT/AUG1 ERROR Incorrect feedback from Auger/Belt 2 BELT/AUG2 ERROR Incorrect feedback from spread symmetry SPREAD SYM ERROR Spread monitoring NO SPREADING! (when enabled) Incorrect spread width (out of range) WIDTH ERROR The audible alarm signal can be switched off with the i key. State S	
	audible alarm signal can be switched off with the i key. aad-density selector switch 1 (Transport 1) isities of 0 - 40 g/m ² for salt or 0 - 240 g/m ² for sand/grit can be set with this rotary switch. Auger/ 1 can be controlled in accordance with the road speed in either closed- or open-loop mode. The erial is preselected with the selector key. Different deposition rates can be set for salt and sand/ (Index 1 in SETUP). In the case of wet salt (On/Off), the transport speed is lowered by the wet-salt uction factor (-W-SALT), which is adjustable. ing blended-materials operation, this density switch determines the total rate of deposition (see) spread-density selector switch 2). If a fault occurs (no feedback), the transporter current is re- ed to 60% of its maximum value I _{max} . The fault message "BELT/AUG 1 FAULT" appears on the valay. After the audible fault alarm has been cancelled, Auger/Belt 1 can be operated again by pres- t the i key on the control system once again. If fill-level sensor 1 is no longer covered (high level), fault message "FILL LEVEL 1" appears on the display. The output is not switched off. ead-density selector switch 2 (Transport 2) Isities of 0 - 40 g/m ² for salt or 0 - 240 g/m ² for sand/grit can be set with this rotary switch. Auger/ 2 or the liquid pump can be controlled by the road speed in either open- or closed-loop mode. In material is preselected with the selector key. Different deposition rates can be set for salt and d/grit (Index 2 in SETUP). In the case of wet salt (On/Off), the rate of deposition is lowered by the -salt reduction factor (-W-SALT), which is adjustable. During blended-materials operation, and with oportional liquid pump in the case of wet salt (e.g. controlling the liquid pump), the required ded quantity (0 to 40%) is set with the rotary switch, and the density of the blended material can set in SETUP using the liquid density. ample settings: Density 1 = 20 g/m ² ; Oensity 2 = 35% e of deposition: Auger 1 = 13 g/m ² (65%); Auge	
¢₽	Spread-width selector switch (spinner) The spread width that is required is set with this rotary switch. A spread-width range of 1 - 9 m or 3 - 12 m can be selected in SETUP. The spinner can be controlled in closed- or open-loop mode. For every spread width, the corresponding speed can be saved in the control system. As soon as the material Sand/Grit is selected for a particular Transport, the spinner speed can be altered by an ad- justable factor. If a fault occurs (no feedback), the spinner current is reduced to I _{min} (SETUP value). The fault message SPINNER FAULT! appears on the display. After the audible fault alarm has been cancelled, the spinner can be operated again by pressing the i key on the control system once again.	
	Spread-symmetry adjustment Two relay outputs are switched in a position-dependent manner with this stepless controller. The drive element can be an electric motor, or a hydraulic cylinder controlled by two on/off solenoid valves. The actual-value feedback is provided by a potentiometer that is mechanically coupled with the drive. If there has been no corresponding movement after 5 seconds, power to the drive is switched off. In the event of a fault, the fault message SPREAD SYM ERROR appears on the display. After the audible signal has been cancelled, the drive can be actuated in the open-loop operating mode by pressing the i key once again. By turning the controller fully to the right or left, the control system allows the drive to be operated in the corresponding direction for a maximum of 4 seconds without requiring any feedback signal. In SETUP, the function can be programmed for closed-loop or open-loop control, or disabled. In addi- tion, both corner points of the adjustment range can be adjusted, as can the hysteresis of the posi- tioning accuracy.	



6.1 Setup - short menu

From software version 2.2, there is a facility for altering some setup parameters without opening the electronic system. If the "ENTER" and "ESC" keys are pressed simultaneously when the vehicle is stationary and spreading is switched off, then the specific densities of the materials, among other parameters, can be set. As in setup mode, the values are adjusted with the rotary switch for Density 1. The values can also be set in the setup mode.

7 Data logging

With the option /01 version of the unit, the operating data is recorded. Through a serial interface, the data can be either output directly by a printer, or transferred to a PC (or mobile data logger) for further processing. If the data is not output online, it is stored in an internal memory that retains its data even when the controller's power supply is switched off. As soon as the data has been output, it is automatically deleted. The data can also be deleted manually via the menu item "Data buffer CLR".

Technical data - interface:

RS232:	connecting cable 1:1
Baud Rate:	2400, 4800, 9600, 19200
Parity:	none
Data Bits:	8
Stop Bits:	1
Format:	ASCII text
Stecker:	SUB-D 9-pin connector

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